

ECCV 2018 (Munich)

Trip report

Kobus Barnard



Interdisciplinary Visual Intelligence Lab
<http://ivilab.org>



Trip reporting

- Expect to give a presentation if you attend a conference, workshop, extended tutorial, etc.

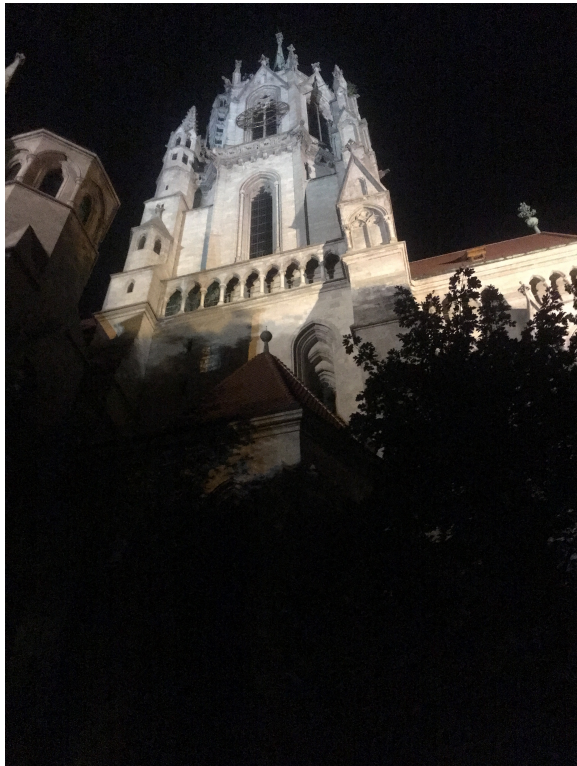
Conferences in CS and AI in particular

- Top conferences are very competitive
- Top vision conferences are: ICCV, CVPR, ECCV
- Top machine learning conferences are NIPS and ICML
- Additional AI conferences are AAAI, ICHCAI, and ICLR
- Posters versus orals
 - Acceptance is usually done first, then orals are chosen
 - Orals give you some bragging rights. They are some of the better papers, but also are chosen to be of more general interest, and fit into a larger balanced schedule.

ECCV 2018 (the explosion continues)

- My first big conference in a while
- We had a paper in ECCV 2016, but I did not go because I waited too long to decide to go (Kyle went).
- ECCV 2018 was capped at 3200 (and was sold out for the last month)
- CVPR 2017 was of the order of 7000
- NIPS sold out in 11 minutes!

Munich



What do you notice walking about?

- People smoke — a lot!
 - Lots of outdoor seating at restaurants
- Commuting by bike (without helmets) is very popular
 - Pedestrians are prey



**Venue: Gasteig,
which is
relatively famous
philharmonic
hall**







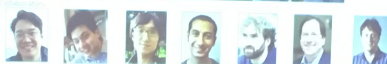
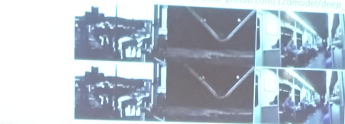




Questions?

Poster No. P-1B-02

Code & Data: github.com/120model/120seg_mnist_seg





MRF OPTIMIZATION WITH SEPARABLE CONVEX PRIOR ON PARTIALLY ORDERED LABELS

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PROBLEM DEFINITION

Given: set of variables \mathcal{V} ; (finite) label set \mathcal{L}
Goal: find a multi-labeling $f: \mathcal{V} \rightarrow \mathcal{L}$, minimizing

$$E(f) = \sum_{i \in \mathcal{V}} E_i(f_i) + \sum_{(i,j) \in \mathcal{E}} E_{ij}(f_i, f_j)$$

Unary terms: $E_i: \mathcal{L} \rightarrow \mathbb{R}$

Pairwise terms: $E_{ij}: \mathcal{L} \times \mathcal{L} \rightarrow \mathbb{R}_0^+$

$$E_{ij}(f_i, f_j) = w_{ij} \cdot d(f_i, f_j),$$

where $w_{ij} \geq 0$ and d is a metric on \mathcal{L}

$E(f)$ can be minimized in polynomial time

1. if $|\mathcal{L}| = 2$, or
2. if \mathcal{L} is a totally ordered set and d is convex

Our assumptions:

- $\mathcal{L} = \mathcal{L}_1 \times \dots \times \mathcal{L}_k$, $k \geq 2$ with totally ordered sets $\mathcal{L}_1, \dots, \mathcal{L}_k$, and
- $d(f_i, f_j) = g(f_i - f_j)$ with an even, separable convex function g

CONTRIBUTIONS

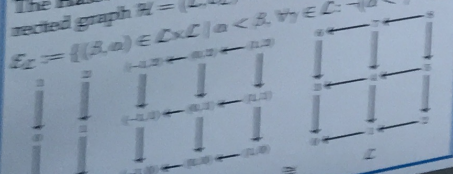
- Extension of Ishikawa's construction: lifted graph-representable energy
- Feasible solution is obtained by move-making
- Efficient coarse-to-fine strategy
- Comparable results at reduced time complexity

POSETS

We call (\mathcal{L}, \leq) a poset if $\forall \alpha, \beta, \gamma \in \mathcal{L}$

- $\alpha \leq \alpha$ (Reflexivity)
- $\alpha \leq \beta, \beta \leq \alpha \Rightarrow \alpha = \beta$ (Antisymmetry)
- $\alpha \leq \beta, \beta \leq \gamma \Rightarrow \alpha \leq \gamma$ (Transitivity)

(\mathcal{L}, \leq) is called a totally ordered set if, for any pair $\alpha, \beta \in \mathcal{L}$ the statement $\alpha \leq \beta$ or $\beta \leq \alpha$ is true
The Hasse diagram of a (finite) poset (\mathcal{L}, \leq) is a directed graph $H = (\mathcal{L}, \mathcal{E}_H)$ with the edge set



LOWER LEVEL SETS AND LOWER IDEALS

For each $\alpha \in \mathcal{L}$ its lower level set is

$$[\alpha] := \{\beta \in \mathcal{L} \mid \beta \leq \alpha\}$$

we obtain that

$$[0] = \{0\}$$

$$[1] = \{0, 1\}$$

$$[2] = \{0, 2\}$$

$$[3] = \{0, 1, 2, 3\} = \mathcal{L}$$

$I \subset \mathcal{L}$ is a lower ideal, if $\alpha \in I \Rightarrow [\alpha] \subset I$

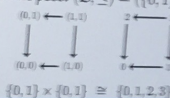
A lower ideal accumulates lower level sets:

$$I = \bigcup_{\alpha \in I} [\alpha]$$

Therefore, $\mathcal{L}_1^* = \{[0], [1], [2], [3]\} \cong \{0, 1, 2, 3\}$

Notations: set of all lower ideals $\mathcal{L}^* \subset 2^{\mathcal{L}}$; set of all lower level sets $\mathcal{L}_1^* \subset \mathcal{L}^*$

Example: for the poset $(\mathcal{L}, \leq) = (\{0, 1\} \times \{0, 1\}, \leq)$



$$\mathcal{L}^* = \mathcal{L}_1^* \cup \{[1] \cup [2]\} \cong \{0, 1, 2, 3, 4, 5\}$$

Augmented label set:

$$\mathcal{L}^A = \mathcal{L}^* - \mathcal{L}_1^* \subset 2^{\mathcal{L}} \Leftrightarrow \mathcal{L}^A = \mathcal{L}_1^* \cup \mathcal{L}^A$$

ENERGY LIFTING

$k = 1$: \mathcal{L} is a totally ordered label set; Ishikawa's graph construction

$k \geq 2$: for a poset $\mathcal{L}_1 \times \dots \times \mathcal{L}_k$ we construct a flow graph $(\mathcal{V} \times \mathcal{L}, \mathcal{E}_D \cup \mathcal{E}_C, c, s, t)$ consisting of

- Constraint edges (\mathcal{E}_C): for each pixel with ∞ capacity based on the Hasse diagram



- Data edges (\mathcal{E}_D): for each vertex (i, f_i) we associate a cost of D_{i,f_i} , resulting in a t -link, such that

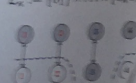
$$\sum_{i \in \mathcal{V}} D_{i,f_i} = E(f_i) \quad \forall i \in \mathcal{V}, f_i \in \mathcal{L}$$

- Smoothness edges (\mathcal{E}_S): we have k even, convex functions g_k

$$d(f_i, f_j) = \sum_{k=1}^k g_k(f_{i,k} - f_{j,k})$$

Adapting Ishikawa's idea: for all $k = 1, \dots, k$ we encode g_k on

$$\mathcal{L}_k = \{0, 1\} \times \dots \times \{0, 1\} \times \mathcal{L}_k$$



L_k penalty: $3 = 2$ nodes connect

Lifted graph-rep

D

such that $D(f_i, f_j)$

A globally

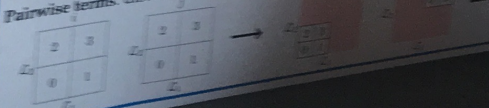
Resolving

select a

COARSE-TO-FINE STRATEGY

Coarse-to-fine approach in the label space instead of the image domain
Unary terms: min pooling over the labels belonging to the same region on

Pairwise terms: distance between the centers of selected regions



NUMERICAL EXPER

Optical flow estimation: $I_1(p_i) = I_2(p_i + f_i)$ for $p_i \in \mathcal{P}$
The energy is adapted from

$$E(f) = \sum_{i \in \mathcal{V}} E_i(f_i) + \sum_{(i,j) \in \mathcal{E}} E_{ij}(f_i, f_j)$$

$E_i(f_i) = 1 - \max(0, \text{NCC}(f_i, I_1 - I_2))$
sensitive Potts model

Post-processing: EpicFlow interpolation

Evaluation: MPI Sintel dataset, 1000 frames

146 x 341 (rescaled by a factor of 1/2)

Evaluation measure: average end-point error

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METHOD

CONTRIBUTIONS

Code

EXPERIMENTS (CONT'D)



Figure 2: Segmentation results on SYNTHIA. From left to right: Input image; Ground truth; Depth + J-Linkage; Depth + Ransacov; Geometric Context; Ours.



Figure 3: Segmentation results on Cityscapes. From left to right: Input image; Ground truth; Depth + J-Linkage; Depth + Ransacov; Ours.

Depth prediction:

Method	Abn Rel	Sq Rel	RMSE	RMSE log $\delta < 1.25$	$\delta < 1.25$	$\delta < 1.25$
SYNTHIA						
Train set mean	0.3959	3.7438	10.6487	0.5138	0.3420	0.6699
DispNet+berHu loss	0.4151	2226.1	6.491	0.0755	0.9912	0.8921
Ours	0.0431	0.3643	2.2405	0.0954	0.9860	0.9976
Cityscapes						
Train set mean	0.2325	4.6558	5.4371	0.5093	0.6127	0.7352
DispNet+berHu loss	0.0835	0.7488	5.1907	0.1429	0.9222	0.9776
Ours	0.1042	1.4938	6.8755	0.1869	0.8909	0.9672



Figure 4: Comparison
columns: Depth

EDCV 2018
European Development Conference
10-12 September 2018

All even poster numbers
between 1 and
53 are now
located on the
1st floor behind
the Carl-Orff-
Foyer!

What is HOT?

Everything!

Social Trends

- Industry is consuming academia!
 - New affiliations that I just learned about
 - Sven Dickinson (doing a 2 year leave at Samsung from UT), Raquel Urtasun (now at Uber), Noah Snavely (50% at Google), ...
- Self-driving cars
 - Bottomless well of money
 - Self-flying personal helicopters and delivery drones
- Industry is starting to dominate computer vision and ML conferences
 - Lots of papers out of the big labs (Google, FAIR, ...)
 - Huge number of nice “booths”



Industry topics that come to mind

- Self-driving cars
- Sports
- Augmented reality
- Mapping
- Data annotation!



Map data at scale
from images
contributed by anyone



You Cannot Serve Two Masters: The Harms of Dual Affiliation

Ben Recht, David A. Forsyth, and Alexei Efros • Aug 9, 2018

Facebook would like to have computer science faculty in AI committed to work 80% of their time in industrial jobs and 20% of their time at their university. They call this scheme “co-employment” or “dual affiliation.” This model assumes people can slice their time and attention like a computer, but people can’t do this. Universities and companies are communities, each with their particular missions and values. The values of these communities are often at odds, and researchers must choose where their main commitment lies. By committing researchers to a particular company’s interests, this new model of employment will harm our colleagues, our discipline, and everyone’s future. Like many harms, it comes with benefits for some. But the harm in this proposal outweighs the benefits. If industry wants to support and grow academic computer science, there are much better ways to achieve this.

The proposal will harm our discipline, because it will distract established talent from the special roles of academics: curiosity driven research. Academic scholarship has an excellent record of pursuing ideas into places that are exciting and productive, even if they don’t result in immediate, tangible benefits and especially if they ruffle the feathers of established, powerful institutions. You can’t do that if 80% of your time is spent not annoying a big company. Though big companies belabor promises of complete intellectual freedom to faculty, that can’t and won’t happen because the purpose of companies is to make money for shareholders.

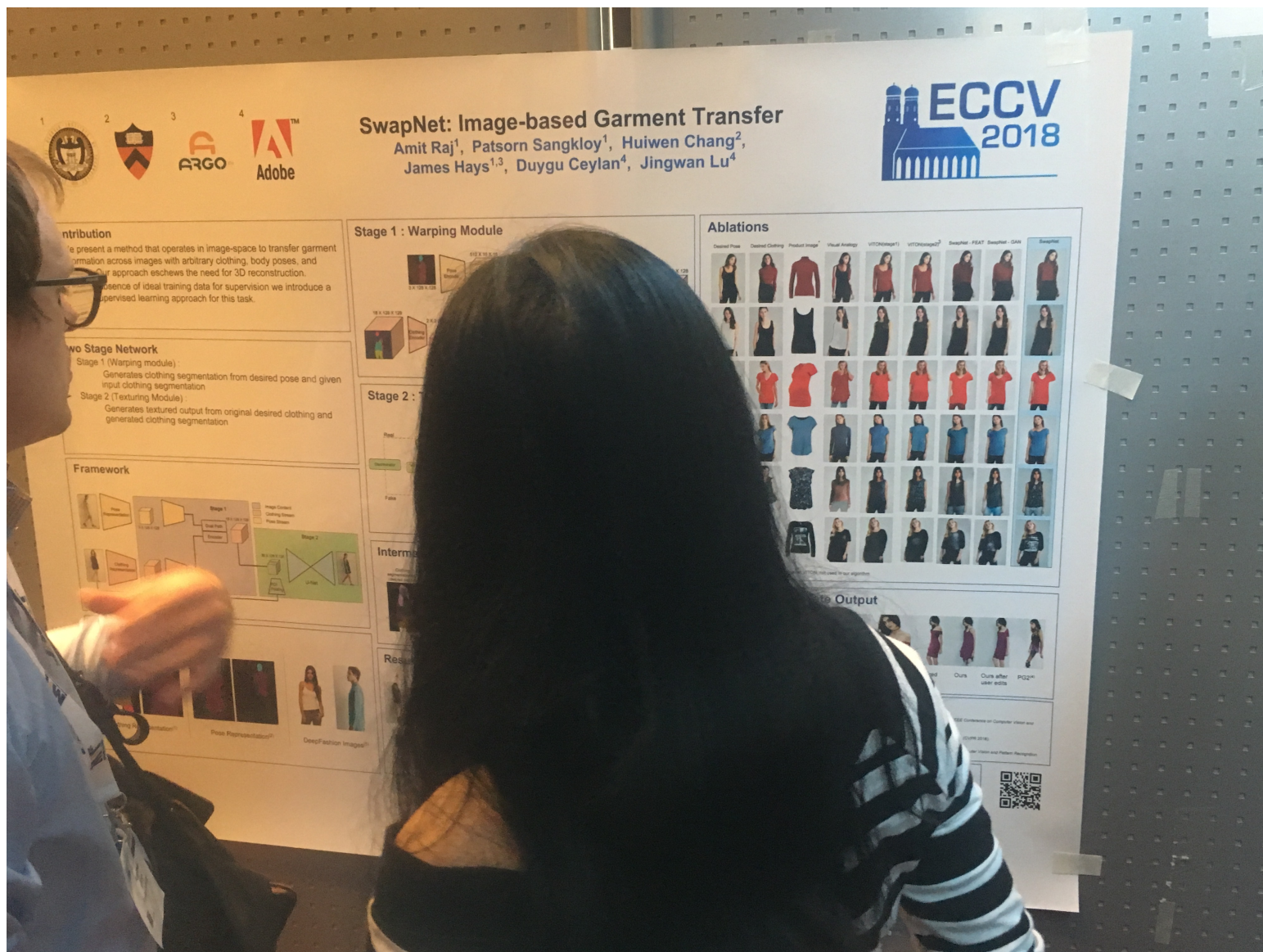
The proposal harms our students directly. Our faculty at their best secure everyone’s future by teaching talented students how to understand the challenges facing the broader world. Such mentorship is enriched by the courage, independence, security, and trained judgement of senior scholars to guide students’ perspectives on what is worth doing, what is likely irrelevant, and what is wrong. Engaging with a student body requires an all-in commitment, both in teaching and advising roles. Faculty primarily working elsewhere means cancelled classes. Faculty wedded to a company means advice that’s colored by the interest of the company.

The proposal harms our future because it will stifle innovation. University researchers have a great historical record of disruptive entrepreneurship — for example, Google dates back to a paper from the Stanford digital library project. Smooth transitions from academic research to industrial practice are widely encouraged: most universities allow faculty to consult at 20% time, do year-long sabbaticals in industry, or take leave to start companies in order to promote such transitions. But there’s a big difference between an industrial leave and a long-term commitment. You can’t do disruptive entrepreneurship if 80% of what you do is owned by a big company. Part of the point of being a big company is to control your environment by crushing, containing, or co-opting inconvenient innovations. Faculty who sign on are subject to a huge gravitational force and are hard pressed not to annoy the big company they work for.

Like many really dangerous bargains, the harms are diffuse, and the benefits are focused. One kind of benefit is for faculty who sign on: in addition to the higher industrial salaries, working at a big company provides a chance to lead a team of research engineers to execute large-scale projects that may be used by millions. But another, more alarming, benefit is for big companies: all those potentially disruptive or potentially annoying ideas are now owned or controlled by the big company. Perhaps that’s the point of why management supports the proposal.

If industry really wants to help scale and advance computer science research, it’s easy to do. Do what many companies are already doing, but do much more of it. Give fellowships to graduate students and scholarships to undergraduate students. Employ students as interns. Pay for named chairs and new buildings. Give lots of faculty small amounts of research money. Make and publish open datasets. Give us easy access to industrial scale computing resources. But don’t raid our faculty and tell us it’s good for us.

Hot fringe topics —swapping clothes



Hot fringe topics — gaze

Carnegie Mellon University
Robotics Institute

Georgia Tech
College of Computing

Deep Stochastic Model for Gaze & Actions

Yin Li*, Miao Liu†, James M. Rehg†

*Carnegie Mellon University, †Georgia Institute of Technology

ECCV 2018
European Conference on Computer Vision

What is the Person Doing?

How can we recognize these actions with % of the pixels missing?

Gaze indexes key visual regions of actions

Needs for a **joint model of gaze and actions**

Deep Stochastic Model for Gaze & Actions

Probabilistic Model

$$p(y|x) = \int_g p(y|g, x) p(g|x) dg$$

- Model gaze as a stochastic unit

Gaze Estimation

$$p(g|x) \sim q(x)$$

- Realized as a neural network

Action Recognition

$$p(y|g, x) = \text{softmax} \left(W_f^T (\sum \tilde{g}_{m,n} \phi(x)_{m,n}) \right)$$

- Weighted average pooling using gaze

Variational Learning

- Gumbel softmax trick
- Loss ~ empirical lower bound

Approximate Inference

- Using the distribution directly
- A tight lower bound

Goal: Gaze & Actions in FPV

Input: Video Clip → Output: Action & Gaze

Challenge: Not all gaze points are relevant to actions (saccade, missing gaze points)

Key idea: Model noisy gaze measurements within deep networks for action recognition

Experiments and Results

EGTEA Gaze+ Dataset

- Gaze tracking + Action labels
- 29 hrs, 32 subjects, 86 sessions

Action Recognition

	Clip Acc*	Vid Acc*
EgoDT+Gaze	N/A	46.50
I3D+Gaze	46.77	51.21
EgoConv+I3D	N/A	48.93
Gaze MLE	47.41	51.12
Ours	47.71	53.30

* Average class accuracy (106 classes)

Gaze Estimation

	F1	Prec	Recall
EgoGaze	16.63	16.63	16.63
Simple Gaze	30.10	25.14	37.48
Deep Gaze	33.51	28.04	41.62
Gaze MLE	24.68	18.55	36.86
Ours	32.97	27.01	42.31

Visualization of Gaze and Actions

Predicted: Cut Cucumber GT: Cut Cucumber Predicted: Take Plate GT: Put Eating Utensil

Predicted: Turn on Faucet GT: Turn on Faucet Predicted: Open Drawer GT: Open Cabinet

Conclusion

- Probabilistic modeling** accounts for uncertainty in gaze signals and improves both gaze & action results
- Jointly modeling of gaze and actions** can significantly benefit action recognition in FPV

Contact: Yin Li, yli440@gatech.edu

Website: https://aptx4869lm.github.io/fpv_gazeactions

The work was done when Y. Li was at Georgia Tech. This research was supported in part by the Intel Science and Technology Center on Pervasive Computing (ISTC-PC).

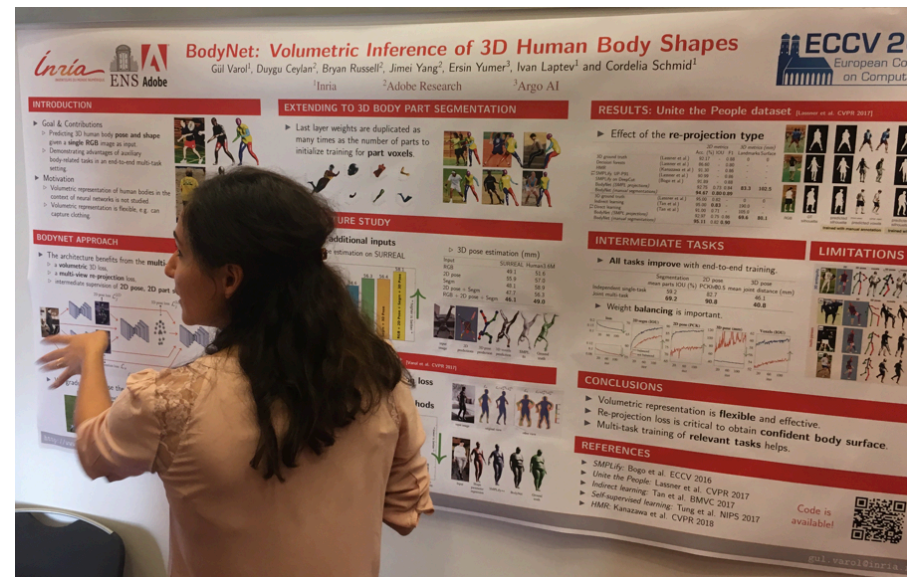
Hot fringe topics

- Swapping cloths
- Gaze
- Augmented reality (e.g., Microsoft HoloLens)
- Any subtopic related to self driving cars
 - EG, finding lanes
- RANSAC
- Explainable deep nets
- Sound and images

Hot main ideas (I)

- Deep Learning
 - Your thing **must** be called “...Net”, e.g., SwapNet, ModelNet, GazeNet, ...

- 3D representation
 - Space filling voxels
 - Meshes



- Deep nets are being built more intelligently, with more vision knowledge built in
 - New phrase: A problem can be “resistant to deepification”

Hot main ideas (II)

- Modular end-to-end
 - Context is self-driving cars
 - Explainability
 - Technical challenge is making the modules differentiable (for training)
- Embodied vision
- Simulation versus reality

Party time











For next week

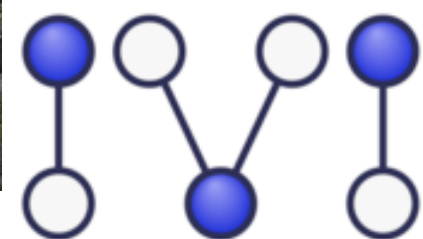
- We will start going through some of the papers
- I have read the title and author list of all them
 - There are only about 750 of them (;-)
- I have selected promising ones on topics like
 - 3D representation (biased towards mesh)
 - State of the art ideas in deep learning
 - Gaze
 - Emotion (e.g., FACS) recognition
 - Optimization

▼	tracking	
		Mir_Rayat_Imtiaz_Hossain_Exploiting_temporal_information_ECCV_2018_paper.pdf
		Efstratios_Gavves_Long-term_Tracking_in_ECCV_2018_paper.pdf
		Chanho_Kim_Multi-object_Tracking_with_ECCV_2018_paper.pdf
▼	sound	
		Ruohan_Gao_Learning_to_Separate_ECCV_2018_paper.pdf
▼	slic	
		Hiroaki_Santo_Light_Structure_from_ECCV_2018_paper.pdf
▼	shrimp	
		Yiming_Qian_Simultaneous_3D_Reconstruction_ECCV_2018_paper.pdf
▼	shape	
		Zorah_Laehner_DeepWrinkles_Accurate_and_ECCV_2018_paper.pdf
		Thomas_Probst_Model-free_Consensus_Maximization_ECCV_2018_paper.pdf
		Thomas_Probst_Incremental_Non-Rigid_Structure-from-Motion_ECCV_2018_paper.pdf
		Nanyang_Wang_Pixel2Mesh_Generating_3D_ECCV_2018_paper.pdf
		Ladicky_From_Point_Clouds_ICCV_2017_paper.pdf
		Jiajun_Wu_Learning_3D_Shape_ECCV_2018_paper.pdf
		Gul_Varol_BodyNet_Volumetric_Inference_ECCV_2018_paper.pdf
		Angjoo_Kanazawa_Learning_Category-Specific_Mesh_ECCV_2018_paper.pdf
▼	scene-geometry-and-physics	
		Zhijian_Liu_Physical_Primitive_Decomposition_ECCV_2018_paper.pdf
		Tianfan_Xue_Seeing_Tree_Structure_ECCV_2018_paper.pdf
		Tian_Ye_Interpretable_Intuitive_Physics_ECCV_2018_paper.pdf
▼	optimization	
		Tat-Jun_Chin_Robust_fitting_in_ECCV_2018_paper.pdf
		Siddharth_Tourani_MPLP_Fast_Parallel_ECCV_2018_paper.pdf
		Csaba_Domokos_MRF_Optimization_with_ECCV_2018_paper.pdf
▼	illumination	
		Zhengqi_Li_CGIntrinsics_Better_Intrinsic_ECCV_2018_paper.pdf
		Wei-Chiu_Single_Image_Intrinsic_ECCV_2018_paper.pdf
▼	human-object-interaction	
		Keizo_Kato_Compositional_Learning_of_ECCV_2018_paper.pdf

- ▼ gaze
 - Tobias_Fischer_RT-GENE_Real-Time_Eye_ECCV_2018_paper.pdf
 - Seonwook_Park_Deep_Pictorial_Gaze_ECCV_2018_paper.pdf
 - Heinonen_Eemeli.pdf
 - Eunji_Chong_Connecting_Gaze_Scene_ECCV_2018_paper.pdf
 - ▶ egocentric
- ▼ fusion
 - Ming_Liang_Deep_Continuous_Fusion_ECCV_2018_paper.pdf
- ▼ face-detailed
 - Weixuan_Chen_DeepPhys_Video-Based_Physiological_ECCV_2018_paper.pdf
 - Ciprian_Corneanu_Deep_Structure_Inference_ECCV_2018_paper.pdf
- ▶ explainable-AI
- ▼ emotion
 - Guosheng_Hu_Deep_Multi-Task_Learning_ECCV_2018_paper.pdf
 - Benitez-Quiroz_EmotioNet_An_Accurate_CVPR_2016_paper.pdf
 - Albert_Pumarola_Anatomically_Coherent_Facial_ECCV_2018_paper.pdf
- ECCV-18-notes.txt.org
- ▼ deep-learning
 - Yuxin_Wu_Group_Normalization_ECCV_2018_paper.pdf
 - Xin_Wang_SkipNet_Learning_Dynamic_ECCV_2018_paper.pdf
 - Viorica_Patraucean_Massively_Parallel_Video_ECCV_2018_paper.pdf
 - Tae-Hyun_Oh_Learning-based_Video_Motion_ECCV_2018_paper.pdf
 - Safa_Cicek_SaaS_Speed_as_ECCV_2018_paper.pdf
 - Rene_Ranftl_Deep_Fundamental_Matrix_ECCV_2018_paper.pdf
 - Ramprasaath_Ramasamy_Selvaraju_Choose_Your_Neuron_ECCV_2018_paper.pdf
 - Pei_Wang_Towards_Realistic_Predictors_ECCV_2018_paper.pdf
 - Navaneeth_Bodla_Semi-supervised_FusedGAN_for_ECCV_2018_paper.pdf
 - Michael_Moeller_Lifting_Layers_Analysis_ECCV_2018_paper.pdf
 - Liang_Mi_Variational_Wasserstein_Clustering_ECCV_2018_paper.pdf
 - Konstantin_Shmelkov_How_good_is_ECCV_2018_paper.pdf
 - Jiqing_Wu_Wasserstein_Divergence_For_ECCV_2018_paper.pdf
 - Gedas_Bertasius_Object_Detection_in_ECCV_2018_paper.pdf
 - Dong_Su_Is_Robustness_the_ECCV_2018_paper.pdf
 - Chenxi_Liu_Progressive_Neural_Architecture_ECCV_2018_paper.pdf
 - Antonio_Torralba_Interpretable_Basis_Decomposition_ECCV_2018_paper.pdf
- bibtex.bib
- ▼ animal-trap
 - Beery_Recognition_in_Terra_ECCV_2018_paper.pdf







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